

# HG-S SERIES

Related Information

- General terms and conditions..... F-3
- Selection guide ..... P.1021~
- Glossary of terms..... P.1587
- General precautions ..... P.1595

- FIBER SENSORS
- LASER SENSORS
- PHOTOELECTRIC SENSORS
- MICRO PHOTOELECTRIC SENSORS
- AREA SENSORS
- SAFETY LIGHT CURTAINS / SAFETY COMPONENTS
- PRESSURE / FLOW SENSORS
- INDUCTIVE PROXIMITY SENSORS
- PARTICULAR USE SENSORS
- SENSOR OPTIONS
- SIMPLE WIRE-SAVING UNITS
- WIRE-SAVING SYSTEMS
- MEASUREMENT SENSORS
- STATIC CONTROL DEVICES
- LASER MARKERS
- PLC
- HUMAN MACHINE INTERFACES
- ENERGY MANAGEMENT SOLUTIONS
- FA COMPONENTS
- MACHINE VISION SYSTEMS
- UV CURING SYSTEMS



## Featuring optical absolute method in the slim and strong unit body

### SENSOR HEAD

#### Robust and slim body contributes to a longer service life

#### Robust and slim body

**Slim body like a pencil type sensor head**

**Hot-swappable**

**Bending-resistant cable**

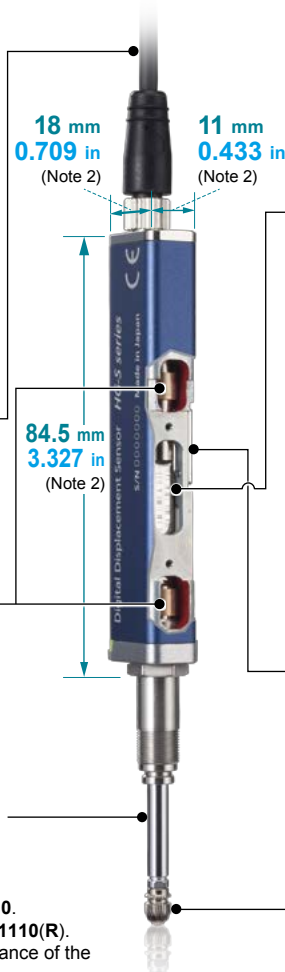
A bending-resistant cable provides peace of mind even when the sensor is installed on a movable tool.

**Plain bearings with 2-point support structure**

A new structure supports the spindle with upper and lower plain bearings to significantly increase rigidity to lateral loads.

**Durability to withstand more than 200 million vertical sliding operations (typical value) (Note 1)**

Notes: 1) Value on HG-S1010 / HG-S1110.  
 2) Value on HG-S1010(R) / HG-S1110(R).  
 3) Value calculated from the clearance of the upper and lower plain bearings.



The slim unit body contains plain bearings with 2-point support structure disperses load and achieves superb durability. The sensor head offers long life and reduces maintenance costs dramatically.

#### Optical absolute method

**No "value skipping" or "unset zero point"**

Displacement is measured by reading a glass scale with a different slit pattern at each reading position using a high-resolution sensor. This eliminates "value skipping" even when measuring at high speed, and there is no concern of "unset zero point".

#### Class-top accuracy

High-precision sensor head [HG-S1110(R)]

<b>Resolution</b> 0.1 μm 0.004 mil	<b>Indication accuracy</b> Full range: 1.0 μm 0.039 mil or less Narrow range: 0.5 μm 0.020 mil or less
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**Resolution**  
No.1\* in class

**Indication accuracy**  
No.1\* in class

\* As of June 2017, in-company survey.

#### Metal guide whirl-stop structure



**Tip deviation amount of 35 μm 1.378 mil or less (typical value) (Note 3) [40 μm 1.575 mil or less (typical value) on the HG-S1032 (Note 3)]**

# Superb craftsmanship!

The accuracy and robustness of the **HG-S** series are backed by master craftsmanship. The plain bearings are accurately aligned with the center of the spindle during their installation to the top and bottom sections of the body to ensure smooth sliding. This process involves careful adjustment of each bearing by a skilled worker. Even though the plain bearing has a certain width, the clearance is managed to the accuracy of several  $\mu\text{m}$ . Those with experience in mechanisms design will know that this value signifies amazingly high control precision. The high-precision, robust sensor is made possible by master craftsmanship. Maximize the high accuracy of our sensors in your pursuit of "ever higher levels of quality."

## Resistance to lateral load

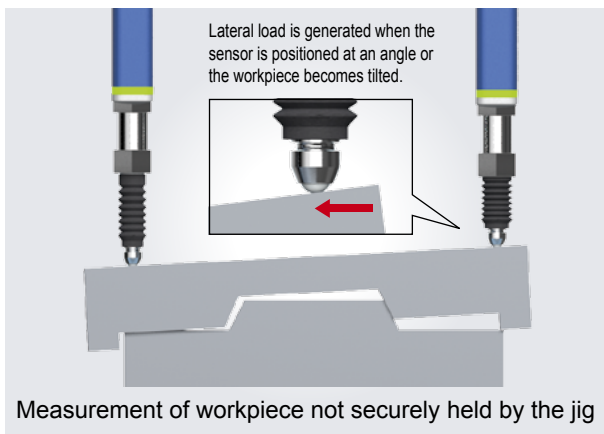
Lateral loads often occur in the workplace, so we conduct our own unique lateral load resistance testing. There is a reason why you can use this product with peace of mind for a long time.

**Withstands more than 100 million sliding operations under application of lateral load (typical value) (Note 1)**

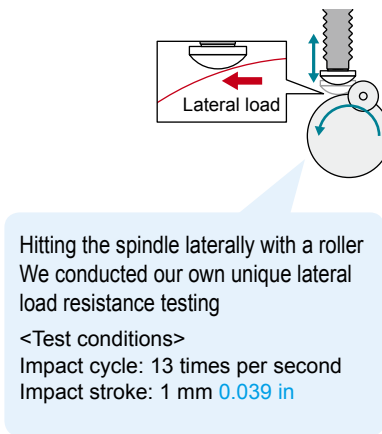
Lateral load resistance  
**No.1\*** in class

\* As of June 2017, in-company survey.

### Example of a lateral load occurring in the workplace



### Lateral load resistance test (Note 2)



Notes:  
1) Value on **HG-S1010** / **HG-S1110**.  
2) Button-type probe for evaluation purposes was installed on the test sample for the lateral load resistance test.

## Resistance to shock and vibration

**Shock resistance: 200 G approx.**

1,960  $\text{m/s}^2$  acceleration in X, Y and Z directions three times each

**Vibration resistance: 20 G approx.**

10 to 500 Hz frequency (**HG-S1032**: 10 to 150 Hz frequency), 3 mm **0.118 in** double amplitude (Maximum acceleration 196  $\text{m/s}^2$ ) in X, Y and Z directions for two hours each

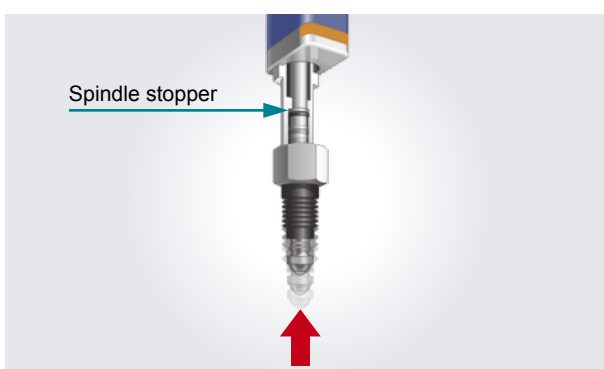
Vibration / shock resistance  
**No.1\*** in class

\* As of June 2017, in-company survey.

## Resistant to upward thrust impact

### Spindle stopper installed at the lower section

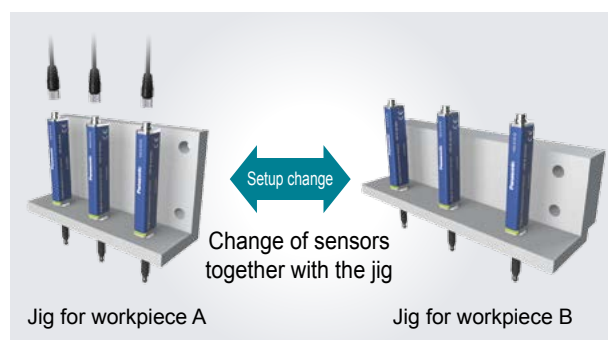
Even if unexpected upward thrust occurs, the lower part of the spindle blocks the impact. Damage to the internal structure, including the glass scale, is minimized.



## Hot-swappable

### Change of sensor head without turning off the power supply

The sensor head can be changed safely without turning off the controller. This reduces the man-hours required for the change of line setup for processing of different workpieces, thus achieving a significant reduction of setup change time.



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PARTICULAR USE SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASUREMENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

PLC

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Selection Guide

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Contact Displacement

Collimated Beam Sensors

Metal-sheet Double-feed Detection

Digital Panel Controller

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- LASER MARKERS
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- MACHINE VISION SYSTEMS
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## CONTROLLER

### Versatile and easy-to-use controller

The controller features the industry's first\* dual display and offers versatile functions and excellent ease of use. It allows simple and reliable operation of the advanced measurement function in a diversity of applications.

\* As a sensor product using optical absolute method, as of September 2015 (according to in-company survey)

#### Dual display for added indication flexibility (equipped with NAVI function)

The 2-line digital display simultaneously shows head measurement (measured value) and judgment value (calculated value).

Industry's first!\*

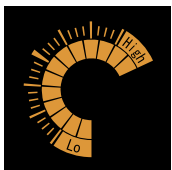
#### High-speed response of 3 ms in combination with any sensor head

#### All-direction LCD

The high-contrast LCD provides sharp and clear indications and wide viewing angle.

#### Equipped with intuitive circle meter

Values between allowable maximum and minimum values are indicated in green. Values outside of the allowable range are indicated in orange. This provides at-a-glance understanding of the margin to the tolerance limits.



Higher than maximum value



Lower than minimum value

#### Anytime selection of function to copy

The selective copy function significantly reduces the man-hours required for initial setting and maintenance.



#### Provided with maintenance mode useful on production floor

The following data are stored and can be used for analysis on the spot.

- Abnormal sensor head upward thrust value
- Number of sensor head upward thrusts
- Cumulative total number of sliding operations

#### Alarm setting for notification of upward thrust

Alarm can be set to notify an upward thrust (stroke) that exceeds the set level. This allows you to conduct a preventive maintenance before the sensor head generates a malfunction.

### Easy-to-understand 2-line digital display

The 2-line digital display simultaneously shows sensor head measurement and judgment value.



Sub-screen: Displays sensor head measurement and other data.

Main screen: Displays judgment value.

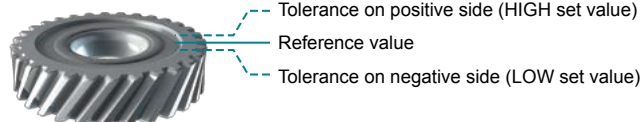
### Easy tolerance setting

#### Simple 1-point teaching

Align with master workpiece and press ENTER key for easy tolerance setting.



One push!

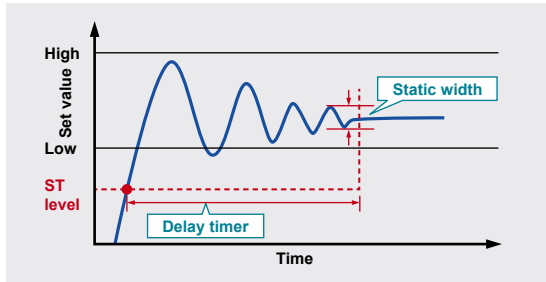


Tolerance setting completed!

## No need for trigger input

### Equipped with self-trigger hold function

Easy setting of time length from measurement start to measurement stabilization.  
Minimizes measurement fluctuation due to the vibration caused by stopping of spindle rotation.



#### (1) Static width setting

Stability range above the ST level can be set as desired.  
Set the range where measurements are considered to be stable.

#### (2) Delay timer setting

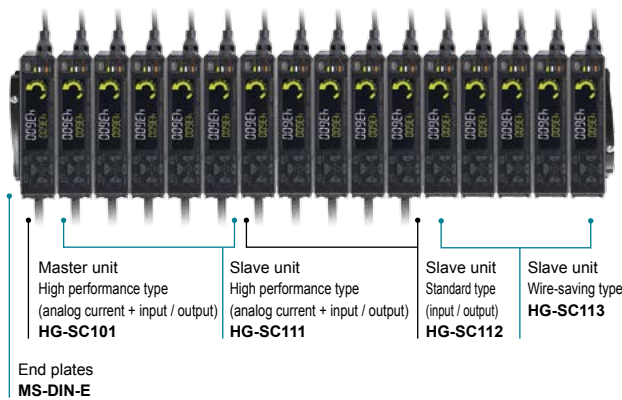
Desired delay time after measurement exceeding the ST level can be set.  
Set the time required for stabilization of measurement.

## Lateral connection of slave units for added operational ease

### Connection of up to 15 slaves units

One master unit can be connected with up to 15 slave units in any order. This allows easy multi-point calculations.

(Example: Connection of 15 slave units)



End plates  
**MS-DIN-E**

\* End plates (optional) must be mounted on both sides of the controller after the connection of slave units.

#### Controller variations

- **Master unit (1 model)**
  - High performance type (analog current + input / output)
- **Slave unit (3 models)**
  - High performance type (analog current + input / output)
  - Standard type (input / output)
  - Wire-saving type

#### Hold function (9 types)

Sample hold (S-H)	Peak hold (P-H)	Bottom hold (B-H)
Peak-to-peak hold (P-P)	Peak-to-peak hold/2 (P-P/2)	
NG hold (NG-H)	Self-sample hold (SLF.S-H)	
Self-peak hold (SLF.P-H)	Self-bottom hold (SLF.B-H)	

#### Calculation function (8 types)

MAX (maximum value)	MIN (minimum value)	FLAT (flatness)	AVERAG (average value)
STAND (reference difference)	TORSIN (torsion)	CURVEA (curvature)	THICK (thickness)

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LASER MARKERS

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**COMMUNICATION UNIT FOR DIGITAL DISPLACEMENT SENSOR**

**Directly send the measurement values of multiple sensors to a host!**

**Communication unit for CC-Link IE Field / CC-Link**

**NEW**

Communication unit for CC-Link IE Field  
**SC-HG1-CEF**



iQSS support is planned

**NEW**

Communication Unit for CC-Link  
**SC-HG1-C**



Supports iQSS

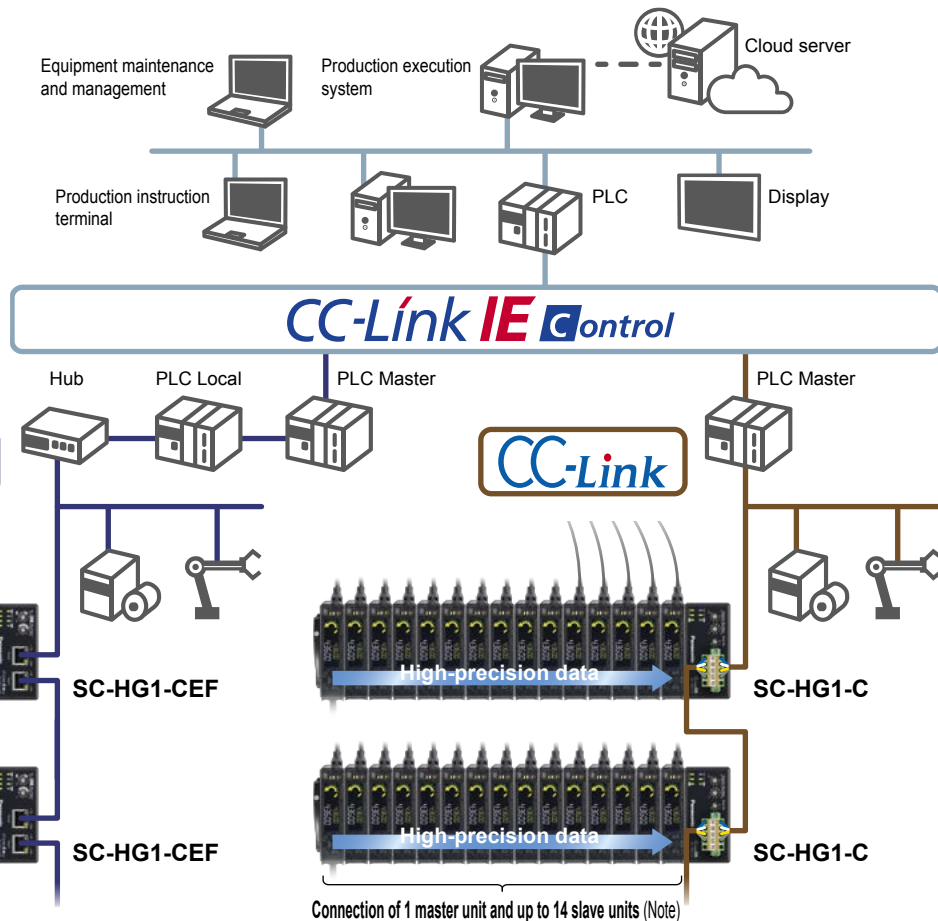
**CC-Link IE Field**

Communication speed: 1 Gbps

**CC-Link**

Communication speed: 10 Mbps (max.)

The communication unit can be used to connect directly to a CC-Link network. This lets you acquire digital data and ON / OFF information in real-time without a program. In addition, you can change controller settings and log measurement data via the CC-Link network, so you can also use the system for preventative maintenance of digital displacement sensors.



**CC-Link IE Field**

**CC-Link**

Connection of 1 master unit and up to 14 slave units (Note)

Connection of 1 master unit and up to 14 slave units (Note)

Note: When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit

**Communication unit for RS-485**

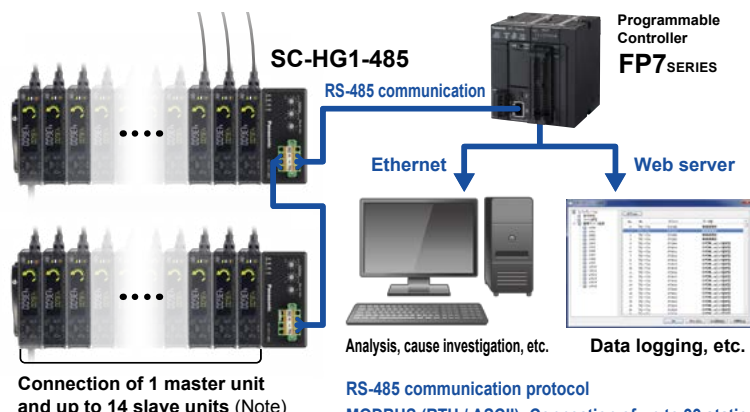
Communication unit for RS-485  
**SC-HG1-485**



Communication speed: 1.2 kbps / 2.4 kbps / 4.8 kbps / 9.6 kbps / 19.2 kbps / 38.4 kbps / 57.6 kbps / 115.2 kbps

For use of high-precision measurement results as traceability data examples. Transfers not only measurements results obtained at multiple points but also setting statuses as digital data in a batch. Provides powerful support to the management of inspection records and identification of failure causes.

Note: When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.



Connection of 1 master unit and up to 14 slave units (Note)

Analysis, cause investigation, etc.

Data logging, etc.

RS-485 communication protocol  
MODBUS (RTU / ASCII): Connection of up to 99 stations  
MEWTocol-COM: Connection of up to 64 stations

**APPLICATIONS**

**AUTOMOTIVE APPLICATIONS**

**OTHER APPLICATIONS**

**Coupling assembly inspection**



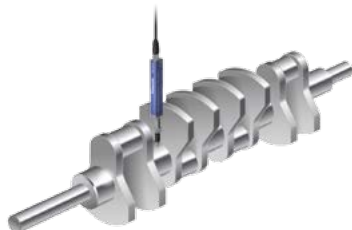
**Installed height measurement**



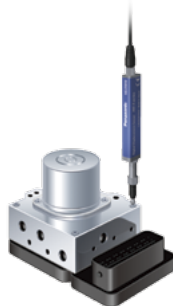
**Motor shaft eccentricity measurement**



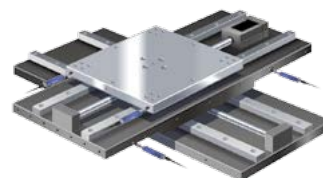
**Crankshaft dimension measurement**



**Screw head height measurement**



**X-Y stage position measurement**



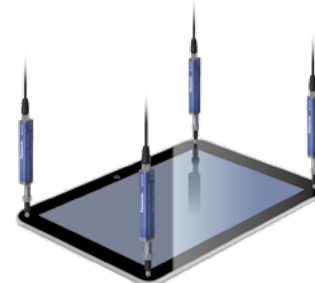
**Transmission parts height measurement**



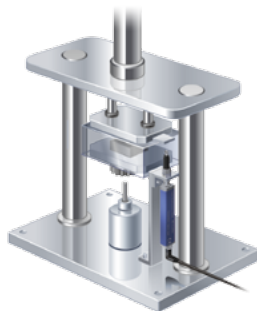
**Automotive parts dimension measurement**



**Tablet surface flatness measurement**



**Management of press-fit points of press-fit parts**



Contact-type displacement sensor and load cell are used to manage pressure change point and stroke position for the confirmation of proper press-fit mounting.

**Resin roller eccentricity measurement**



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PLC

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

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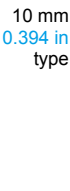

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## ORDER GUIDE




### Sensor heads

Type			Appearance	Measurement range	Resolution	Model No.
10 mm 0.394 in type	General purpose	Standard	<b>General purpose</b>  32 mm 1.260 in type	10 mm 0.394 in	0.5 μm 0.020 mil	<b>HG-S1010</b>
		Low measuring force				<b>HG-S1010R</b>
	High precision	Standard	<b>High precision</b>  10 mm 0.394 in type		0.1 μm 0.004 mil	<b>HG-S1110</b>
		Low measuring force				<b>HG-S1110R</b>
32 mm 1.260 in type	General purpose	Standard	 32 mm 1.260 in type	32 mm 1.260 in	0.5 μm 0.020 mil	<b>HG-S1032</b>

### Sensor head connection cables (bending-resistant type)

Type	Appearance	Cable length	Model No.
Straight connector		3 m 9.843 ft	<b>CN-HS-C3</b>
		7 m 22.966 ft	<b>CN-HS-C7</b>
		20 m 65.617 ft	<b>CN-HS-C20</b>
L-shaped connector		3 m 9.843 ft	<b>CN-HS-C3L</b>
		7 m 22.966 ft	<b>CN-HS-C7L</b>
		20 m 65.617 ft	<b>CN-HS-C20L</b>




### Controllers

Type		Appearance	Model No.	Output	Maximum number of connectable controllers
Master unit	High performance type (analog current + input / output)		<b>HG-SC101</b>	NPN open-collector transistor	Up to 15 slave units can be connected per master unit (Note)
			<b>HG-SC101-P</b>	PNP open-collector transistor	
Slave units	High performance type (analog current + input / output)		<b>HG-SC111</b>	NPN open-collector transistor	
			<b>HG-SC111-P</b>	PNP open-collector transistor	
	Standard type (input / output)		<b>HG-SC112</b>	NPN open-collector transistor	
			<b>HG-SC112-P</b>	PNP open-collector transistor	
Wire-saving type			<b>HG-SC113</b>	—	


Note: When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.

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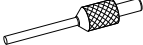




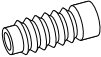

**ORDER GUIDE****Communication units for digital displacement sensors**

Designation	Appearance	Model No.	Description
Communication unit for CC-Link IE Field		<b>SC-HG1-CEF</b>	Can directly send high-precision measurement values to a CC-Link IE Field host device. <ul style="list-style-type: none"> <li>• Communication method CC-Link IE Field</li> <li>• Number of connected units Host (CC-Link IE Field): Max. 121 units (1 master station, 120 slave stations) Controllers: Maximum of 15 units (1 master, 14 slaves) per <b>SC-HG1-CEF</b> unit</li> </ul>
Communication unit for CC-Link		<b>SC-HG1-C</b>	Can directly send high-precision measurement values to CC-Link Master. <ul style="list-style-type: none"> <li>• Communication method Switchable CC-Link Ver.1.10 or 2.00</li> <li>• Number of occupied station CC-Link Ver.1.10: 4 stations, CC-Link Ver.2.00: Switchable 2 or 4 stations</li> <li>• Number of connected units Controllers: Maximum of 15 units (1 master, 14 slaves) per <b>SC-HG1-C</b> unit</li> </ul>
Communication unit for RS-485		<b>SC-HG1-485</b>	Can directly send high-precision measurement values by RS-485 communication <ul style="list-style-type: none"> <li>• Communication protocol MODBUS (RTU / ASCII) / MEWTOCOL-COM</li> <li>• Number of connected units Host (RS-485): 1 to 99 units when MODBUS (RTU / ASCII) is used, 1 to 64 units when MEWTOCOL-COM is used Controllers: Maximum of 15 units (1 master, 14 slaves) per <b>SC-HG1-485</b> unit</li> </ul>

**End plates**

Designation	Appearance	Model No.	Description
End plates		<b>MS-DIN-E</b> 2 pcs. per set	Always use this when connecting controllers and a digital displacement sensor communication unit.

**OPTIONS****Options (made-to-order)**

Designation	Appearance	Model No.	Description
Probe		<b>TR-S10-C×5</b> 5 pcs. per set	Standard type
		<b>TR-S10-H</b>	Super-hard type
		<b>TR-S321-H</b>	Super-hard needle type
		<b>TR-S411-K</b>	Flat-seated type
		<b>TR-S601</b>	Roller type
Joint		<b>TR-J102</b>	Length 15 mm 0.591 in type
		<b>TR-J104</b>	Length 25 mm 0.984 in type
Rubber bellows		<b>TR-G20×5</b> 5 pcs. per set	_____
Computer software for CC-Link / CC-Link IE Field		<b>SC-PC1</b>	This software makes it possible to use a computer to monitor current sensor values, save setting information to a CSV file, display log data, save log data to a CSV file, etc. Applicable models: <b>SC-HG1-C</b> , <b>SC-HG1-CEF</b> , <b>SC-GU3-01</b> and <b>SC-GU3-04</b> (Note)

Note: For **SC-GU3-01** and **SC-GU3-04**, refer to the communication unit for open network **SC-GU3** series (p.971~).



## SPECIFICATIONS

### Sensor heads

Type		10 mm 0.394 in type				32 mm 1.260 in type
		General purpose		High precision		General purpose
		Standard	Low measuring force	Standard	Low measuring force	Standard
Item	Model No.	HG-S1010	HG-S1010R	HG-S1110	HG-S1110R	HG-S1032
CE marking directive compliance		EMC Directive, RoHS Directive				
Compatible controller		HG-SC101(-P), HG-SC111(-P), HG-SC112(-P), HG-SC113				
Position detection method		Optical absolute linear encoder method				
Measurement range		10 mm 0.394 in				32 mm 1.260 in
Stroke		10.5 mm 0.413 in or more				32.5 mm 1.280 in or more
Measuring force (Note 2)	Downward mount	1.65 N or less 1.10 N (Note 3)	0.35 N or less 0.30 N (Note 3)	1.65 N or less 1.10 N (Note 3)	0.35 N or less 0.30 N (Note 3)	2.97 N or less 1.90 N (Note 3)
	Upward mount	1.35 N or less 0.85 N (Note 3)	—	1.35 N or less 0.85 N (Note 3)	—	2.09 N or less 1.19 N (Note 3)
	Side mount	1.50 N or less 0.95 N (Note 3)	0.25 N or less 0.20 N (Note 3)	1.50 N or less 0.95 N (Note 3)	0.25 N or less 0.20 N (Note 3)	2.53 N or less 1.50 N (Note 3)
Resolution		0.5 µm 0.020 mil		0.1 µm 0.004 mil		0.5 µm 0.020 mil
Sampling period		1 ms				
Indication accuracy (P-P)		Full range: 2.0 µm 0.079 mil or less Narrow range: 1.0 µm 0.039 mil or less (any 60 µm 2.362 mil)		Full range: 1.0 µm 0.039 mil or less Narrow range: 0.5 µm 0.020 mil or less (any 60 µm 2.362 mil)		Full range: 3.0 µm 0.118 mil or less Narrow range: 2.0 µm 0.079 mil or less (any 60 µm 2.362 mil)
Tip deviation amount		35 µm 1.378 mil (typical) (Note 4)				40 µm 1.575 mil (typical) (Note 4)
Hot swap function		Incorporated				
Operation indicator		2-color LED (Orange / Green)				
Environmental resistance	Protection	IP67 (IEC) (Note 5)	—	IP67 (IEC) (Note 5)	—	IP67 (IEC) (Note 5)
	Ambient temperature	-10 to +55 °C +14 to +131 °F (No condensation or icing allowed), Storage: -20 to +60 °C -4 to +140 °F				
	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH				
	Insulation resistance	100 MΩ or more at 250 V DC				
	Vibration resistance	10 to 500 Hz frequency (HG-S1032: 10 to 150 Hz frequency), 3 mm 0.118 in double amplitude (Maximum acceleration 196 m/s <sup>2</sup> ) in X, Y and Z directions for two hours each				
	Shock resistance	1,960 m/s <sup>2</sup> acceleration in X, Y and Z directions three times each				
Mounting nut tightening strength		12.5 N·m				15 N·m
Probe tightening torque		0.1 to 0.4 N·m (no force applied to main unit)				
Grounding method		Capacitor grounding				
Material		Body: Zinc (HG-S1032: Aluminum), Holder: Stainless steel, Spindle: Tool steel (HG-S1032: Free-cutting steel), Probe (Note 6): Ceramic, Rubber bellows: NBR (black)				
Weight		Net weight: 80 g approx.				Net weight: 150 g approx.
Accessories		Standard type (HG-S1010 / HG-S1110 / HG-S1032): Sensor head fastening wrench 1 pc., Mounting nut 1 pc. Low measuring force type (HG-S1010R / HG-S1110R): Sensor head fastening wrench 1 pc., Mounting nut 1 pc., Rubber bellows 1 pc.				

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: standard type measurement probe (TR-S10-C), ambient temperature +20 °C +68 °F, and a clean atmosphere where dust and liquids such as water and oil do not come in contact with the equipment.  
2) In the case of low measurement force type (HG-S1010R / HG-S1110R), measurements were obtained with products in standard configuration without rubber bellows.  
3) Typical value near center of measurement.  
4) Value calculated from the clearance of the upper and lower plain bearings.  
5) Excludes damage and deterioration to rubber bellows due to external causes.  
6) The probes (optional) are also available.

**SPECIFICATIONS****Controller**

Item	Model No.	Type	Master unit		Slave unit				
			NPN output	PNP output	High-performance type	High-performance type	Standard type	Wire-saving type	
			<b>HG-SC101</b>	<b>HG-SC101-P</b>	<b>HG-SC111</b>	<b>HG-SC111-P</b>	<b>HG-SC112</b>	<b>HG-SC112-P</b>	<b>HG-SC113</b>
CE marking directive compliance			EMC Directive, RoHS Directive						
Compatible sensor head			<b>HG-S1010(R), HG-S1110(R), HG-S1032</b>						
Number of connectable units			Up to 15 slave units can be connected per master unit. (Note 2)						
Supply voltage			24 V DC $\pm 10\%$ , including ripple 0.5 V (P-P)						
Current consumption (Note 3)			70 mA or less (when sensor head is connected)						
Analog current output (Note 4)			Current output range: 4 to 20 mA/F.S. (default value) Error output: 0 mA Linearity: $\pm 0.25\%$ F.S. Load impedance: 250 $\Omega$ max.						
Control outputs (Output 1, Output 2, Output 3)			<NPN output type> NPN open-collector transistor • Maximum sink current: 50 mA (Note 5) • Applied voltage: 30 V DC or less (between output and 0 V) • Residual voltage: 1.5 V or less (at 50 mA sink current) • Leakage current: 0.1 mA or less		<PNP output type> PNP open-collector transistor • Maximum source current: 50 mA (Note 5) • Applied voltage: 30 V DC or less (between output and +V) • Residual voltage: 1.5 V or less (at 50 mA source current) • Leakage current: 0.1 mA or less				
Short-circuit protection			Incorporated (automatic reset type)						
Judgment output			NO / NC switching method						
Alarm output			Open when alarm occurs						
External inputs (Input 1, Input 2, Input 3)			<NPN output type> Non-contact input or NPN open-collector transistor • Input condition: Invalid (+8 V to +V DC or open) Valid (0 to +1.2 V DC) • Input impedance: 10 k $\Omega$ approx.		<PNP output type> Non-contact input or PNP open-collector transistor • Input condition: Invalid (0 to +0.6 V DC or open) Valid (+4 V to +V DC) • Input impedance: 10 k $\Omega$ approx.				
Trigger input			Input time 2 ms or more (ON)						
Preset input			Input time 20 ms or more (ON)						
Reset input			Input time 20 ms or more (ON)						
Bank input A / B (Note 6)			Input time 20 ms or more (ON)						
Response time			3 ms, 5 ms, 10 ms, 100 ms, 500 ms, 1,000 ms switching type						
Digital display			204-segment LCD						
Display resolution			0.1 $\mu\text{m}$ <b>0.004 mil</b>						
Display range			-199.9999 to 199.9999 mm <b>-7.874 to 7.874 in</b>						
Contamination level			2						
Elevation			2,000 m <b>6561.68 ft</b> or less (Note 7)						
Protection			IP40 (IEC)						
Ambient temperature			-10 to +50 °C <b>+14 to +122 °F</b> (No dew condensation or icing allowed) (Note 5), Storage: -20 to +60 °C <b>-4 to +140 °F</b>						
Ambient humidity			35 to 85 % RH, Storage: 35 to 85 % RH						
Voltage withstandability			1,000 V AC for one min. between all supply terminals connected together and enclosure						
Insulation resistance			20 M $\Omega$ , or more, with 250 V DC megger between all supply terminals connected together and enclosure						
Vibration resistance			10 to 150 Hz frequency, 0.75 mm <b>0.030 in</b> double amplitude (Maximum acceleration 49 m/s <sup>2</sup> ) in X, Y and Z directions for two hours each						
Shock resistance			98 m/s <sup>2</sup> acceleration (10 G approx.) in X, Y and Z directions five times each						
Material			Case: Polycarbonate, Cover: Polycarbonate, Switches: Polyacetal						
Cable			0.2 mm <sup>2</sup> 2-core cable (brown and blue lead wires) / 0.15 mm <sup>2</sup> 7-core composite cable, 2 m <b>6.562 ft</b> long	0.15 mm <sup>2</sup> , 7-core composite cable, 2 m <b>6.562 ft</b> long	0.15 mm <sup>2</sup> , 6-core cable cable, 2 m <b>6.562 ft</b> long				
Weight			Net weight: 140 g approx.	Net weight: 140 g approx.	Net weight: 130 g approx.	Net weight: 60 g approx.			

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C **+68 °F**.

2) When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.

3) Current consumption does not include analog current output.

4) Linearity F.S. = 16 mA, and is linearity with respect to digitally measured values.

5) When slave units are connected to the master unit, the maximum sink current / source current of the control output and ambient temperature vary depending on the number of connected slave units as shown below.

Number of connected slave units	Maximum sink current / source current of control output	Ambient temperature
1 to 7 units	20 mA	-10 to +45 °C <b>+14 to +113 °F</b>
8 to 15 units	10 mA	

6) Banks 1 to 3 can be selected by switching bank input A / B.

7) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

**SPECIFICATIONS**

**Communication units for digital displacement sensors**

Designation	Communication unit for CC-Link IE Field	
Item	Model No.	<b>SC-HG1-CEF</b>
CE marking directive compliance	EMC Directive, RoHS Directive	
Compatible controllers	<b>HG-SC</b> □	
Maximum number of connectable controllers	Maximum of 15 controllers (one master, 14 slaves) per <b>SC-HG1-CEF</b> unit	
Supply voltage (Note 2)	24 V DC ±10%, including ripple 0.5 V (P-P)	
Current consumption	200 mA or less	
Communication method	CC-Link IE Field	
Remote station type	Remote device station	
Network No. setting	1 to 239 (decimal) [1 to EF (hex)] (0 and 240 or more: Error) (Note 3)	
Cyclic transmission (Maximum number of links per station)	RX / RY: 128 points each (128 bits), 16 bytes RW / RWw: 64 points each (64 words), 128 bytes	
Transient transmission	Server function only, data size 1,024 bytes	
Station No. setting	1 to 120 (decimal) (0 and 121 or more: Error)	
Baud rate	1 Gbps	
Transmission line types	Line, star (mixing of line and star types is possible), ring	
Maximum transmission distance	100 m <b>328.084 ft</b>	
Maximum number of connectable units	121 units (1 master station, 120 slave stations)	
Cascade connection levels	Maximum 20	
Pollution degree	2	
Operating altitude	2,000 m <b>6561.680 ft</b> or less (Note 4)	
Environmental resistance	Protection	IP40 (IEC)
	Ambient temperature	-10 to +45 °C <b>+14 to +113 °F</b> (No dew condensation or icing allowed) Storage: -20 to +60 °C <b>-4 to +140 °F</b>
	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH
	Voltage withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure
	Insulation resistance	20 MΩ or more, with 250 V DC megger between all supply terminals connected together and enclosure
	Vibration resistance	10 to 150 Hz frequency, 0.75 mm <b>0.030 in</b> double amplitude in X, Y and Z directions for two hours each
	Shock resistance	98 m/s <sup>2</sup> acceleration (10 G approx.) in X, Y and Z directions five times each
	Material	Enclosure: Polycarbonate
	Communication cable	Ethernet cable that satisfies 1000BASE-T standard Category 5e or higher (Double-shielded / STP, straight cable) (Note 5)
	Weight	Net weight: 100 g approx., Gross weight: 150 g approx.

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C **+68 °F**.  
 2) Power is supplied from a connected controller / master controller.  
 3) For the network No. setting on this product, convert the network number to hex and set the hex value.  
 4) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.  
 5) Use CC-Link Partner Association recommended cable.

Designation	Communication unit for CC-Link					
Item	Model No.	<b>SC-HG1-C</b>				
CE marking directive compliance	EMC Directive (Note 2), RoHS Directive					
Compatible controllers	<b>HG-SC</b> □					
Maximum number of connectable controllers	Maximum of 15 controllers (one master, 14 slaves) per <b>SC-HG1-C</b> unit					
Supply voltage (Note 3)	24 V DC ±10 %, including ripple 0.5 V (P-P)					
Current consumption	80 mA or less					
Communication method	Switchable CC-Link Ver.1.10 or 2.00					
Remote station type	Remote device station					
Number of occupied station	CC-Link Ver.1.10: 4 stations, CC-Link Ver.2.00: Switchable 2 or 4 stations					
Station No. setting	1 to 64 (0 and 65 or more: Error)					
Baud rate	10 Mbps	5 Mbps	2.5 Mbps	625 kbps	156 kbps	
Maximum transmission distance	100 m <b>328.084 ft</b>	160 m <b>524.934 ft</b>	400 m <b>1,312.336 ft</b>	900 m <b>2,952.756 ft</b>	1,200 m <b>3,937.008 ft</b>	
Pollution degree	2					
Operating altitude	2,000 m <b>6561.680 ft</b> or less (Note 4)					
Environmental resistance	Protection	IP40 (IEC)				
	Ambient temperature	-10 to +45 °C <b>+14 to +113 °F</b> (No dew condensation or icing allowed), Storage: -20 to +60 °C <b>-4 to +140 °F</b>				
	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH				
	Voltage withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure				
	Insulation resistance	20 MΩ or more, with 250 V DC megger between all supply terminals connected together and enclosure				
	Vibration resistance	10 to 150 Hz frequency, 0.75 mm <b>0.030 in</b> double amplitude in X, Y and Z directions for two hours each				
	Shock resistance	98 m/s <sup>2</sup> acceleration (10 G approx.) in X, Y and Z directions five times each				
	Material	Enclosure: Polycarbonate				
	Communication cable	Specified cable (shielded twisted cable) (Note 5)				
	Weight	Net weight: 80 g approx., Gross weight: 130 g approx.				

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C **+68 °F**.  
 2) If our product will be incorporated in a customer product that will comply with the EMC Directive, install our product in a conductive box in accordance with "PLC User's Manual [Published by Mitsubishi Electric Corporation]".  
 3) Power is supplied from a connected controller / master controller.  
 4) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.  
 5) Use only a special-use communication cable that is approved by the CC-Link Partner Association.

Designation	Communication unit for RS-485		
Item	Model No.	<b>SC-HG1-485</b>	
CE marking directive compliance	EMC Directive, RoHS Directive		
Compatible controllers	<b>HG-SC</b> □		
Supply voltage (Note 2)	24 V DC ±10 %, Ripple P-P 10 % or less (Within specified power supply voltage range)		
Current consumption	40 mA or less		
Communication method	Two-wire half duplex communication		
Synchronization method	Start-stop synchronization		
Communication protocol	MODBUS (RTU / ASCII) / MEWTOCOL-COM		
Baud rate	1.2 kbps / 2.4 kbps / 4.8 kbps / 9.6 kbps / 19.2 kbps / 38.4 kbps / 57.6 kbps / 115.2 kbps		
Electrical characteristics	Complies with EIA RS-485		
Number of connectable units	Host (RS-485)	1 to 99 units when MODBUS (RTU / ASCII) is used, 1 to 64 units when MEWTOCOL-COM is used	
	Sensors	Maximum of 15 controllers (1 master, 14 slaves) per <b>SC-HG1-485</b> unit	
Stop bit length	1 bit / 2 bits		
Parity check	Even / Odd / None		
Data bit length	8 bits (RTU) / 7 bits (ASCII)		
Pollution degree	2		
Operating altitude	2,000 m <b>6561.68 ft</b> or less (Note 3)		
Environmental resistance	Protection	IP40 (IEC)	
	Ambient temperature	-10 to +45 °C <b>14 to +113 °F</b> (No dew condensation or icing allowed), Storage: -20 to +60 °C <b>-4 to +140 °F</b>	
	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH	
	Voltage withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure	
	Insulation resistance	20 MΩ, or more, with 250 V DC megger between all supply terminals connected together and enclosure	
	Vibration resistance	10 to 150 Hz frequency, 0.75 mm <b>0.030 in</b> double amplitude in X, Y and Z directions for two hours each	
	Shock resistance	98 m/s <sup>2</sup> acceleration (10 G approx.) in X, Y and Z directions five times each	
	Material	Enclosure: Polycarbonate	
	Total extension distance	Communication cable: 1,200 m <b>3,937.008 ft</b> or less between <b>SC-HG1-485</b> (terminal) and PLC	
	Weight	Net weight: 75 g approx., Gross weight: 120 g approx.	
Accessory	Termination resistor switching jumper pin: 1 pc.		

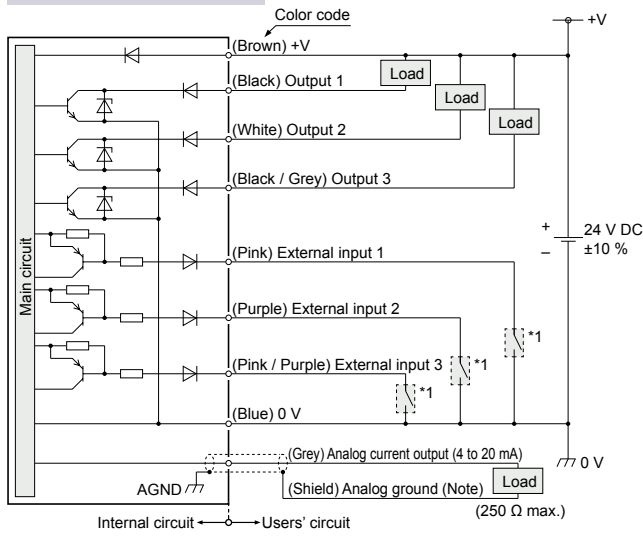
- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C **+68 °F**.  
 2) Power is supplied from a connected controller / master controller.  
 3) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

**I/O CIRCUIT DIAGRAMS**

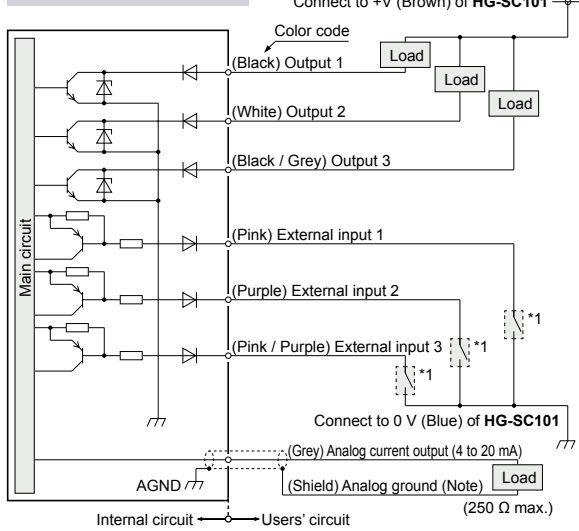
For communication unit for digital displacement sensors, refer to the User's Manual.  
The User's Manual can be downloaded from our website.

**NPN output type**

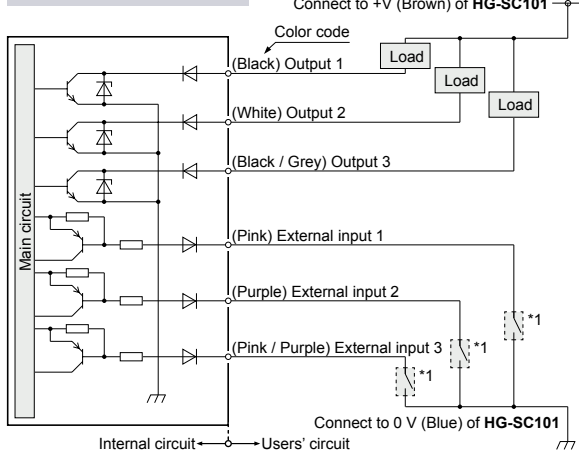
**HG-SC101 / Master unit**



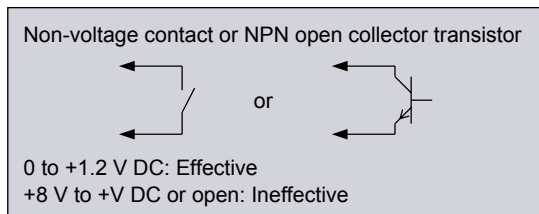
**HG-SC111 / Slave unit**



**HG-SC112 / Slave unit**



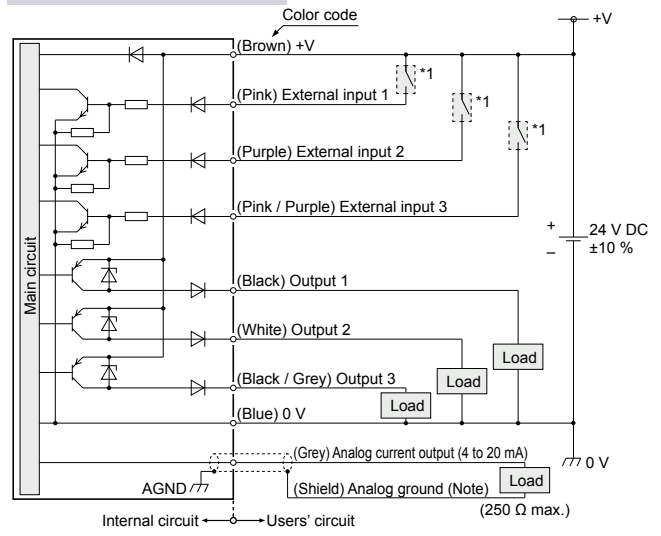
\* 1



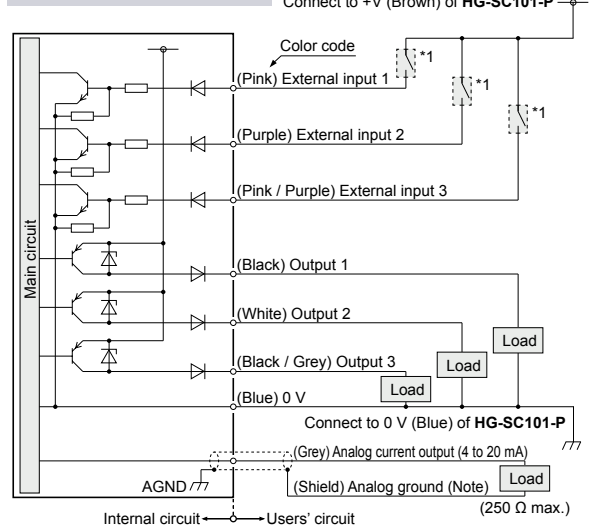
Note: Use shielded wire for the analog output.

**PNP output type**

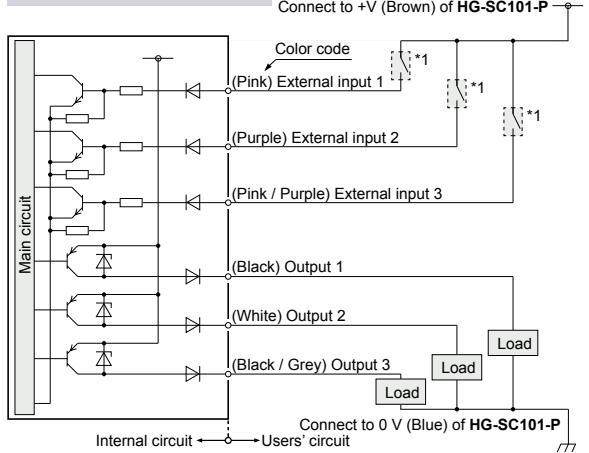
**HG-SC101-P / Master unit**



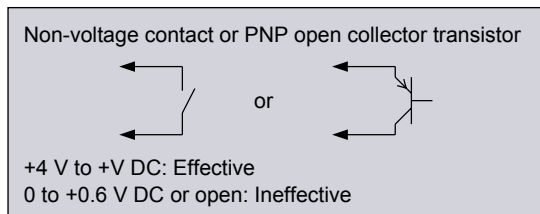
**HG-SC111-P / Slave unit**



**HG-SC112-P / Slave unit**



\* 1



Note: Use shielded wire for the analog output.

FIBER SENSORS

LASER SENSORS

PHOTO-ELECTRIC SENSORS

MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS/ SAFETY COMPONENTS

PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS

WIRE- SAVING UNITS

WIRE- SAVING SYSTEMS

MEASURE- MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

PLC

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Selection Guide

Laser Displacement

Magnetic Displacement

Contact Displacement

Collimated Beam Sensors

Metal-sheet Double-feed Detection

Digital Panel Controller

Other Products

**HG-S**

Refer to the user's manual for details. The user's manual can be downloaded from our website. Refer to p.1595 for general precautions.

**PRECAUTIONS FOR PROPER USE**



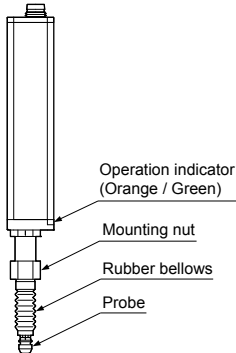
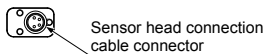
- Never use this product as a sensing device for personnel protection.
- When using sensing devices for personnel protection, use products that meet the laws and standards for personnel protection that apply in each region or country, such as OSHA, ANSI and IEC.

• This catalog has been prepared to aid selection of appropriate products. When using the product, be sure to read the user's manual.

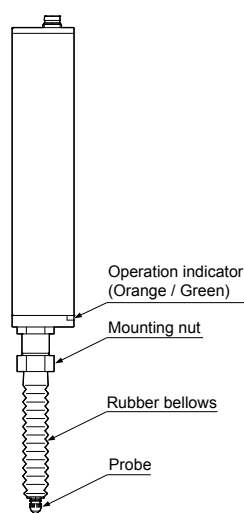
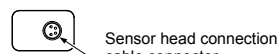
**Part description**

**Sensor head**

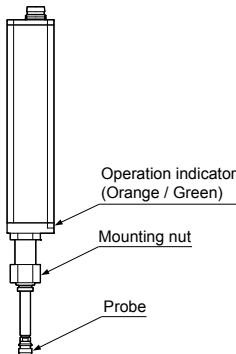
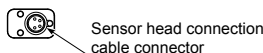
<Standard type>  
(HG-S1010 / HG-S1110)



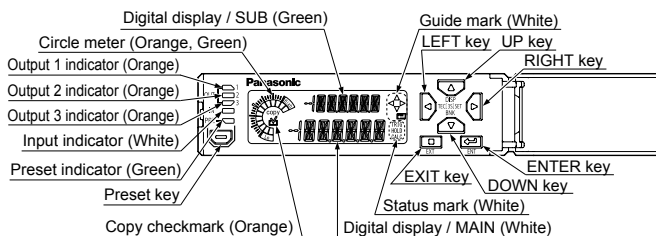
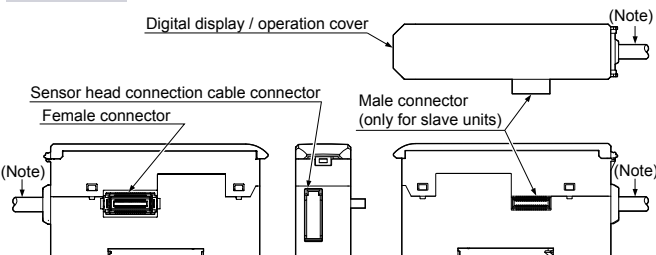
<Standard type>  
(HG-S1032)



<Low measuring force type>  
(HG-S1010R / HG-S1110R)



**Controller**



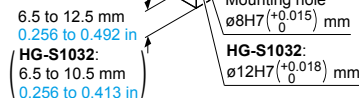
Note: Not provided on slave units or wire-saving type (HG-SC113).

**Sensor head**

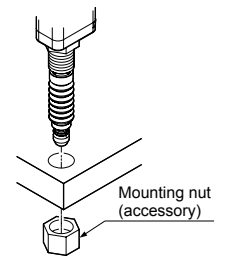
**Mounting**

- When tightening the nut, take care not to damage the rubber bellows.
- If the rubber bellows is deformed, a load will occur when the spindle operates and damage may result.
- Do not remove the rubber bellows from the standard type products (HG-S1010 / HG-S1110 / HG-S1032) except for when replacing them. Unnecessary removal of rubber bellows can result in entry of dust and water, thus causing malfunction.

1. Open a hole in the housing in which the sensor head will be mounted.

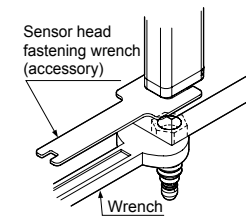


2. Insert the sensor head into the hole you opened in the housing, and fasten provisionally with the provided mounting nut.

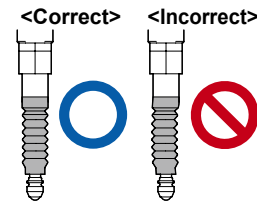


Note: The orientation of the mounting nut depends on the thickness of the housing. For details, refer to DIMENSIONS (p.1107~).

3. Fasten the sensor head. When fastening the sensor head, tighten the mounting nut with a wrench while holding the sensor head in place with the provided sensor head fastening wrench as shown right. Tighten to a torque of 12.5 N·m or less. (HG-S1032: 15 N·m or less)



4. Make sure that the rubber bellows has not become deformed as shown right. If the rubber bellows is deformed, restore the normal shape by rotating the bellows or otherwise.

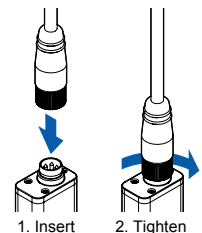


**Attaching the sensor head connection cable**

- When disconnecting, always make sure that the fastening ring has been completely loosened before pulling out the cable.
- Risk of damage if you pull the cable with excessive force (15 N or more) with the fastening ring tightened.

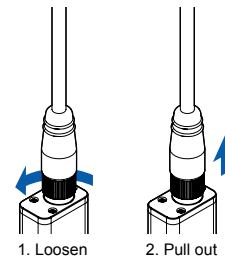
**Mounting**

1. Insert the sensor head connection cable into the connector for the sensor head connection cable on the sensor head.
2. Turn the fastening ring on the sensor head connector in the direction shown to fasten the ring.



**Removal method**

1. Turn the fastening ring on the sensor head connector in the direction of the arrow to loosen the ring.
2. Grasp the sensor head connector and pull up to remove.

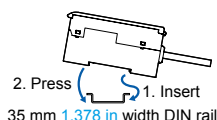


**PRECAUTIONS FOR PROPER USE**

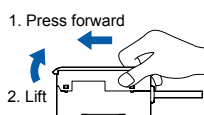
Refer to the user's manual for details. The user's manual can be downloaded from our website.  
Refer to p.1595 for general precautions.

**Controller****Mounting****Mounting**

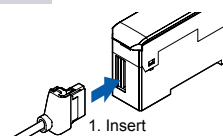
1. Insert the rear of the mounting part into the DIN rail.
2. While pressing down on the rear of the mounting part, insert the front of the mounting part into the DIN rail.

**Removal method**

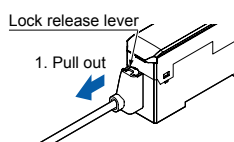
1. Grasp the product and push forward.
2. Lift the front to remove.

**Attaching the sensor head connection cable****Mounting**

1. Insert the sensor head connection cable into the connector for the sensor head connection cable on the controller.

**Removal method**

1. Grasp the controller, and while pressing on the lock release lever on the connector of the sensor head connection cable, pull toward you to disconnect.



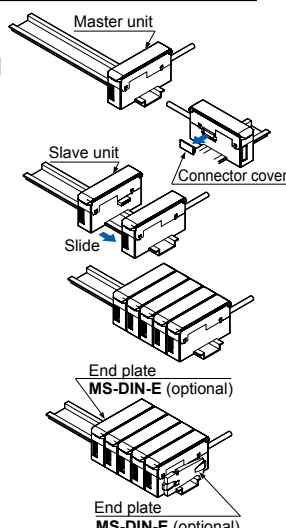
Note: If you attempt to disconnect the cable by pulling it without pressing the lock release lever, cable wire breakage and connector damage may occur.

**Connection**

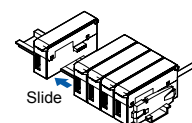
- Always shut off the power before connecting a slave unit to or disconnecting a slave unit from the master unit. Risk of controller damage if you attempt connection with the power on.
- Insert the male connector firmly into the female connector. Risk of controller damage if not completely connected.
- To connect units, the units must be mounted on a DIN rail. Attach end plates **MS-DIN-E** (optional) so as to enclose the connected units at the ends.
- Up to 15 slave units (up to 14 slave units when a communication unit for digital displacement sensor is connected) can be connected per master unit.
- When connecting slave units to a master unit, connect only NPN output types, or only PNP output types. Dissimilar output types cannot be connected together.

**Connection method**

1. Mount one master unit on the DIN rail.
2. Remove the connector cover.
3. Mount each slave unit one at a time on the DIN rail. Remove all connector covers except for the cover on the end slave unit.
4. Slide each slave unit to connect the female and male connectors.
5. Attach end plates **MS-DIN-E** (optional) with the flat side facing in so as to enclose the connected units at the ends.
6. Tighten the screws to fasten the end plates.

**Removal method**

1. Loosen the screws on the end plates
2. Remove the end plates.
3. Slide and remove the controllers, one at a time.

**Common****Wiring**

- The product is designed to fulfill the specifications when combined with the **HG-S** sensor head and **HG-SC** controller. If the product is used in combination with other products, it not only fails to meet the specifications but also generates a malfunction in some cases.
- For the controller DC power supply, only use a power supply that is isolated by means of an isolation transformer or otherwise.
- Risk of short-circuiting and damage to the controller or power supply if a transformer such as an auto transformer is used. Risk of short-circuiting and damage to the controller or power supply if incorrectly mounted or connected.

- Make sure that the power supply is off while performing wiring or expansion work.
- After you have completed wiring work, check the wiring carefully before switching on the power.
- Do not run the wires together with high-voltage lines or power lines or put them in the same raceway. This can cause malfunction due to induction.
- Verify that the supply voltage variation is within the rating.
- If power is supplied from a commercial switching regulator, ensure that the frame ground (F.G.) terminal of the power supply is connected to an actual ground.
- Do not use during the initial transient time after the power supply is switched on.
- Make sure that stress by forcible bend or pulling is not applied directly to the sensor cable joint.

**Others**

- This device has been developed / produced for industrial use only.
- Do not use this product outside the range of the specifications. Risk of an accident and product damage. There is also a risk of a noticeable reduction of service life.
- This controller uses an EEPROM. The EEPROM has a service life of one million setting operations.
- This product is suitable for indoor use only.
- Avoid dust, dirt, and steam.
- Take care that the product does not come in direct contact with organic solvents such as thinner.
- Take care that the product does not come in direct contact with strong acid or alkaline.
- Take care that the product does not come in direct contact with oil or grease.
- Do not use in an environment containing inflammable or explosive gases.
- Performance may not be satisfactory in a strong electromagnetic field.
- This product is a precision device. Do not drop or otherwise subject to shock. Risk of product damage.
- Never attempt to disassemble, repair, or modify the product.

FIBER SENSORS

LASER SENSORS

PHOTO-ELECTRIC SENSORS

MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS

PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

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SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

PLC

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Selection Guide

Laser Displacement

Magnetic Displacement

Contact Displacement

Collimated Beam Sensors

Metal-sheet Double-feed Detection

Digital Panel Controller

Other Products

**HG-S**

**DIMENSIONS (Unit: mm in)**

The CAD data can be downloaded from our website.

- FIBER SENSORS
- LASER SENSORS
- PHOTO-ELECTRIC SENSORS
- MICRO PHOTO-ELECTRIC SENSORS
- AREA SENSORS
- SAFETY LIGHT CURTAINS / SAFETY COMPONENTS
- PRESSURE / FLOW SENSORS
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**HG-S1010(R) HG-S1110(R)**

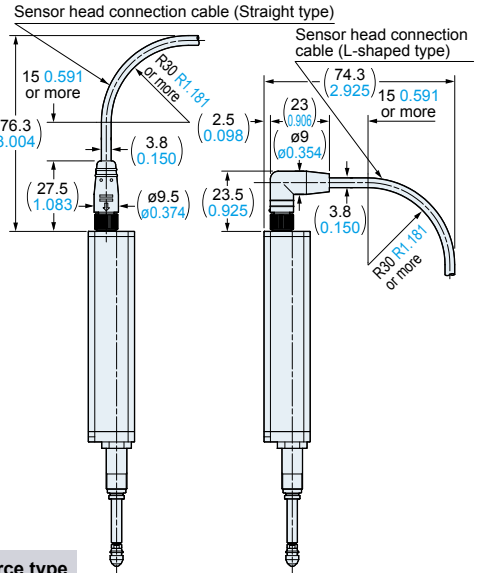
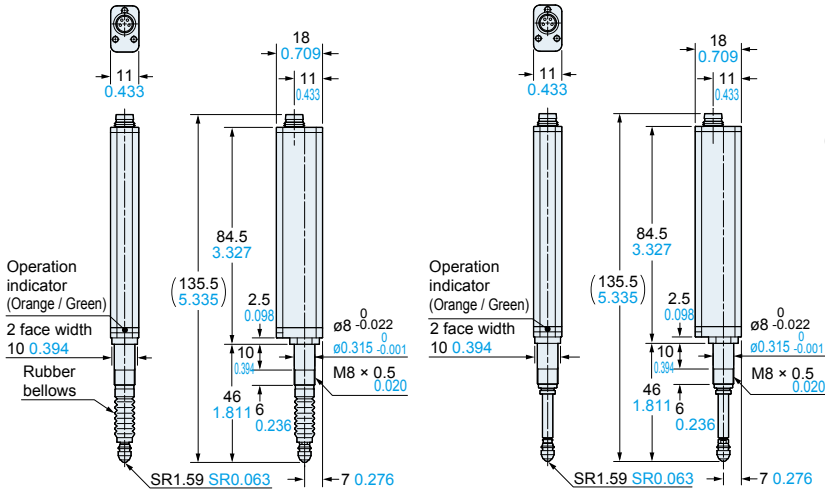
Sensor head

**Standard type  
HG-S1010 / HG-S1110**

**Low measuring force type  
HG-S1010R / HG-S1110R**

**Installation of sensor head connection cable**

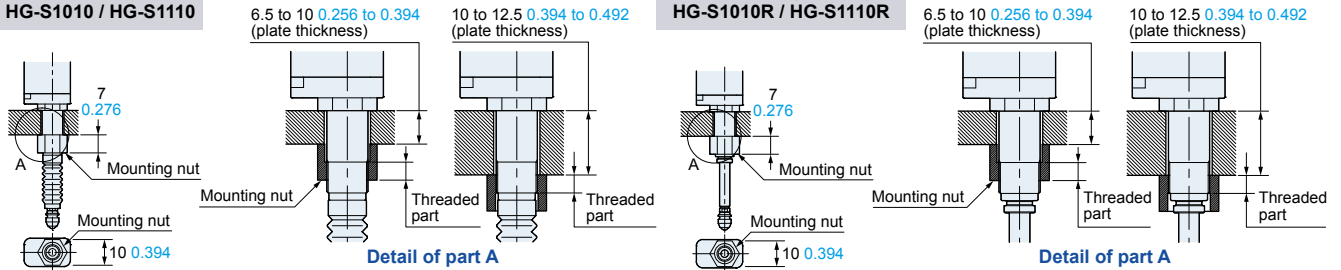
The diagrams show the sensor head connection cable connected to the low measurement force type.



**Installation of mounting nut attachment**

**Standard type  
HG-S1010 / HG-S1110**

**Low measuring force type  
HG-S1010R / HG-S1110R**

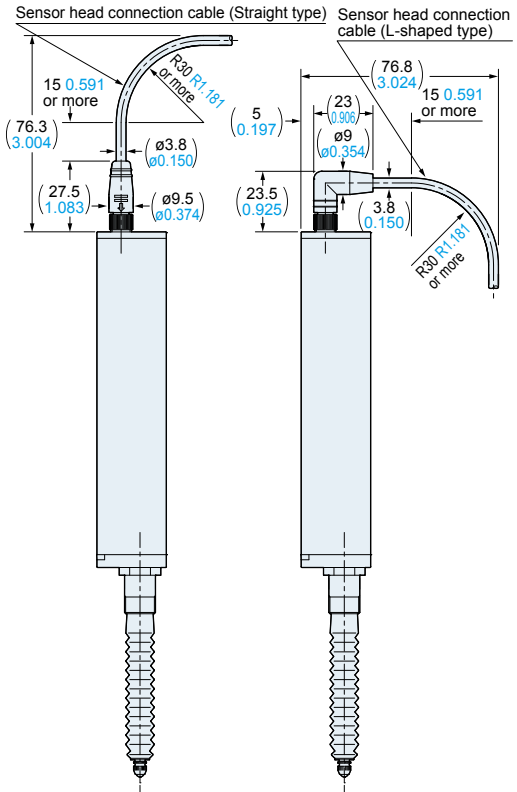
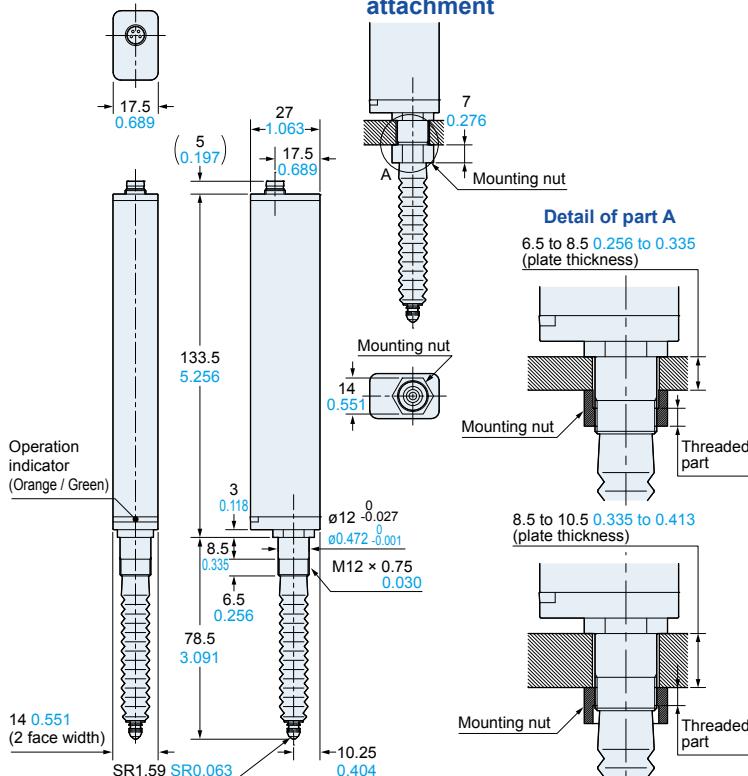


**HG-S1032**

Sensor head

**Installation of mounting nut attachment**

**Installation of sensor head connection cable**

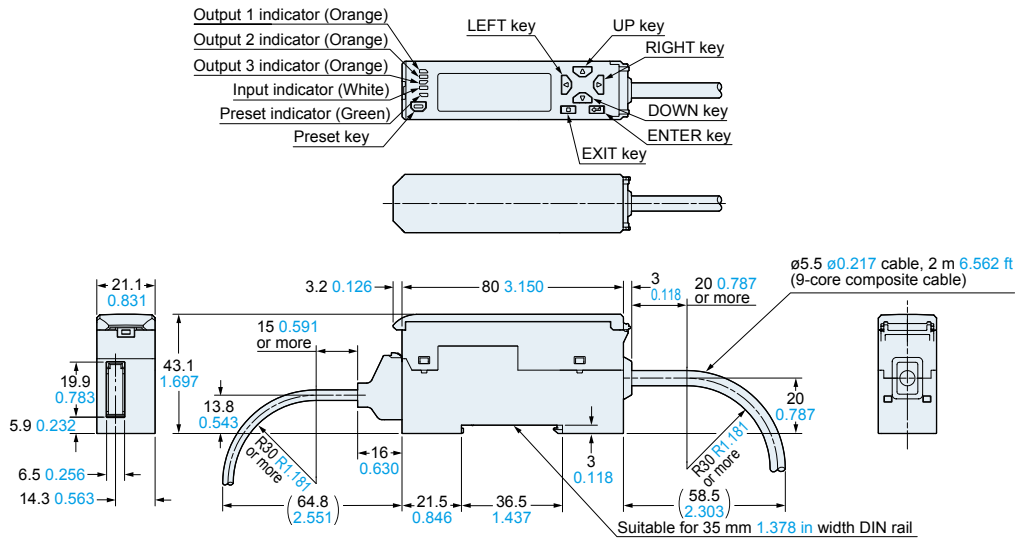


**DIMENSIONS (Unit: mm in)**

The CAD data can be downloaded from our website.

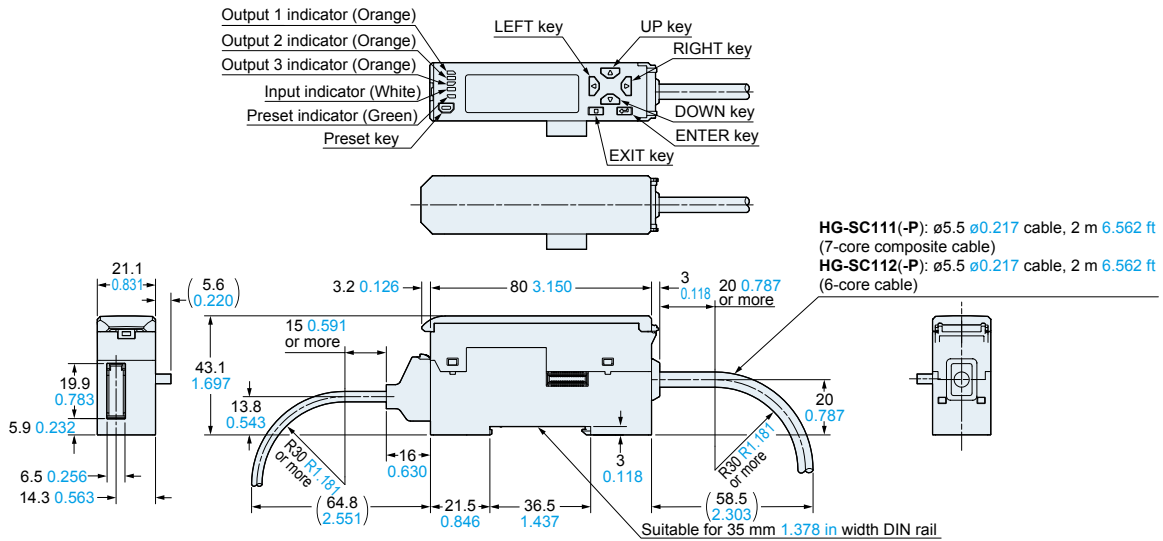
**HG-SC101(-P)**

Controller (Master unit)



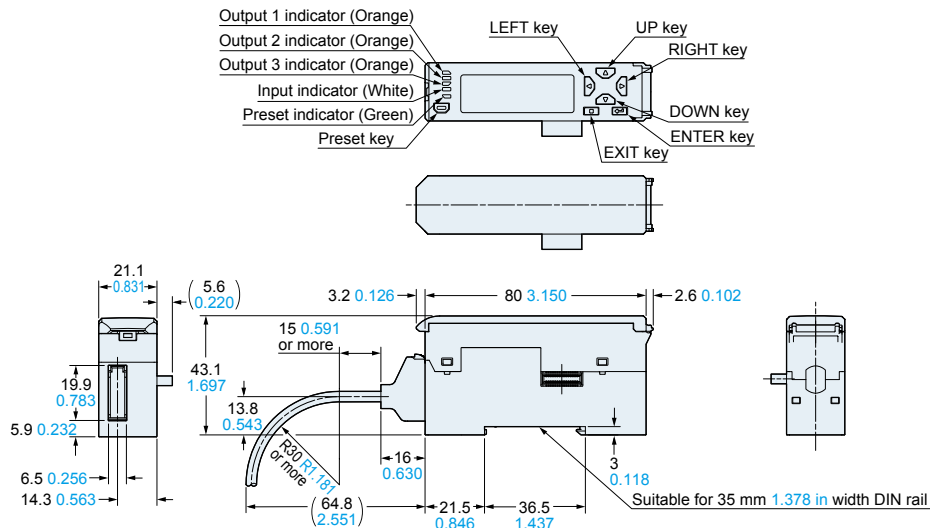
**HG-SC111(-P) HG-SC112(-P)**

Controller (Slave unit)



**HG-SC113**

Controller (Slave unit)



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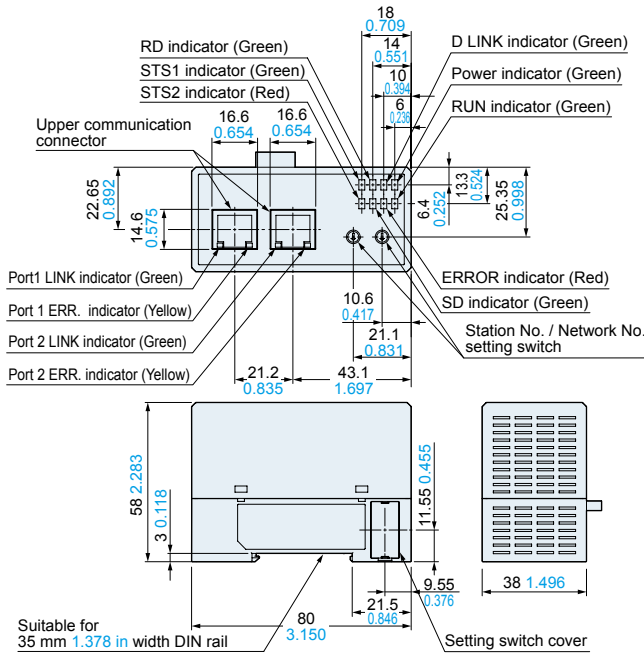
**HG-S**



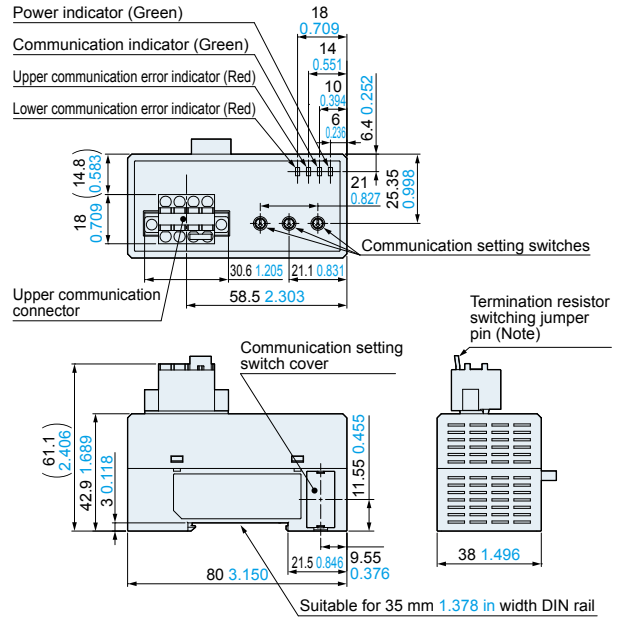
**DIMENSIONS (Unit: mm in)**

The CAD data can be downloaded from our website.

**SC-HG1-CEF** Communication unit for CC-Link IE Field

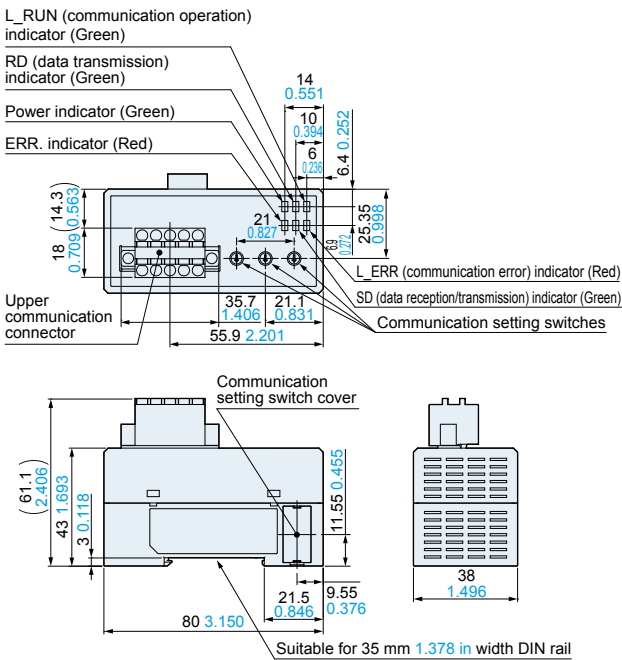


**SC-HG1-485** Communication unit for RS-485

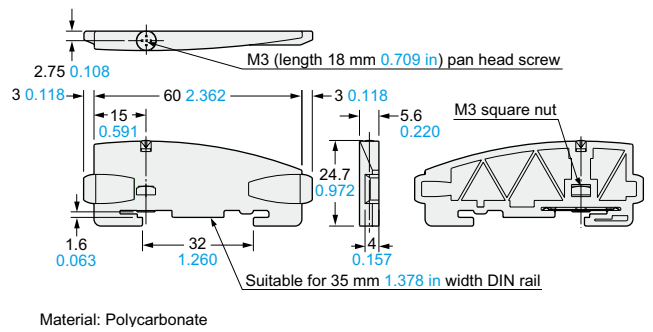


Note: The termination resistor switching jumper pin is not attached to the product at the factory. Attach the termination resistor switching jumper pin to the unit at the terminating end. Make sure that the termination resistor switching jumper pin have been removed from all units except the one at the terminating end.

**SC-HG1-C** Communication unit for CC-Link



**MS-DIN-E** End plate



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**HG-S**

MEMO

A large, empty grid of graph paper, consisting of many small squares, intended for writing a memo.